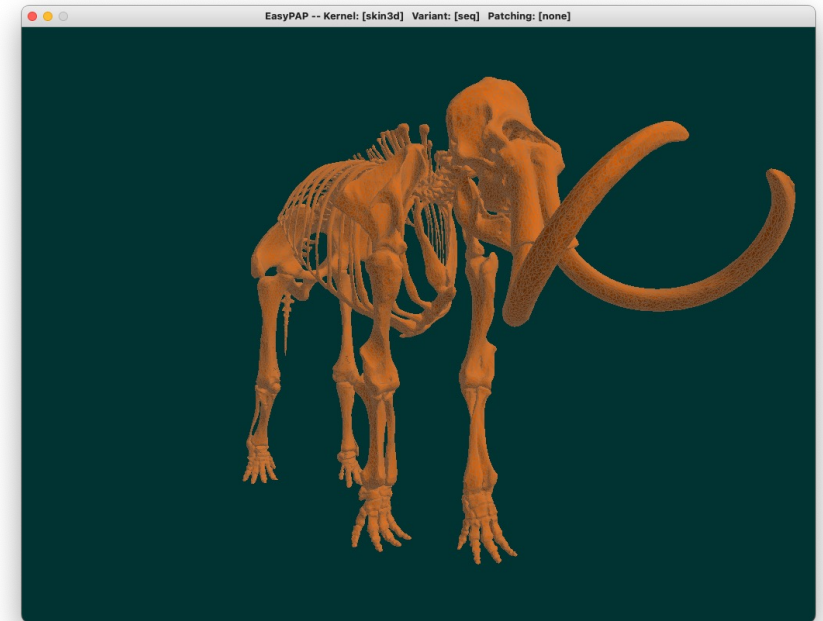


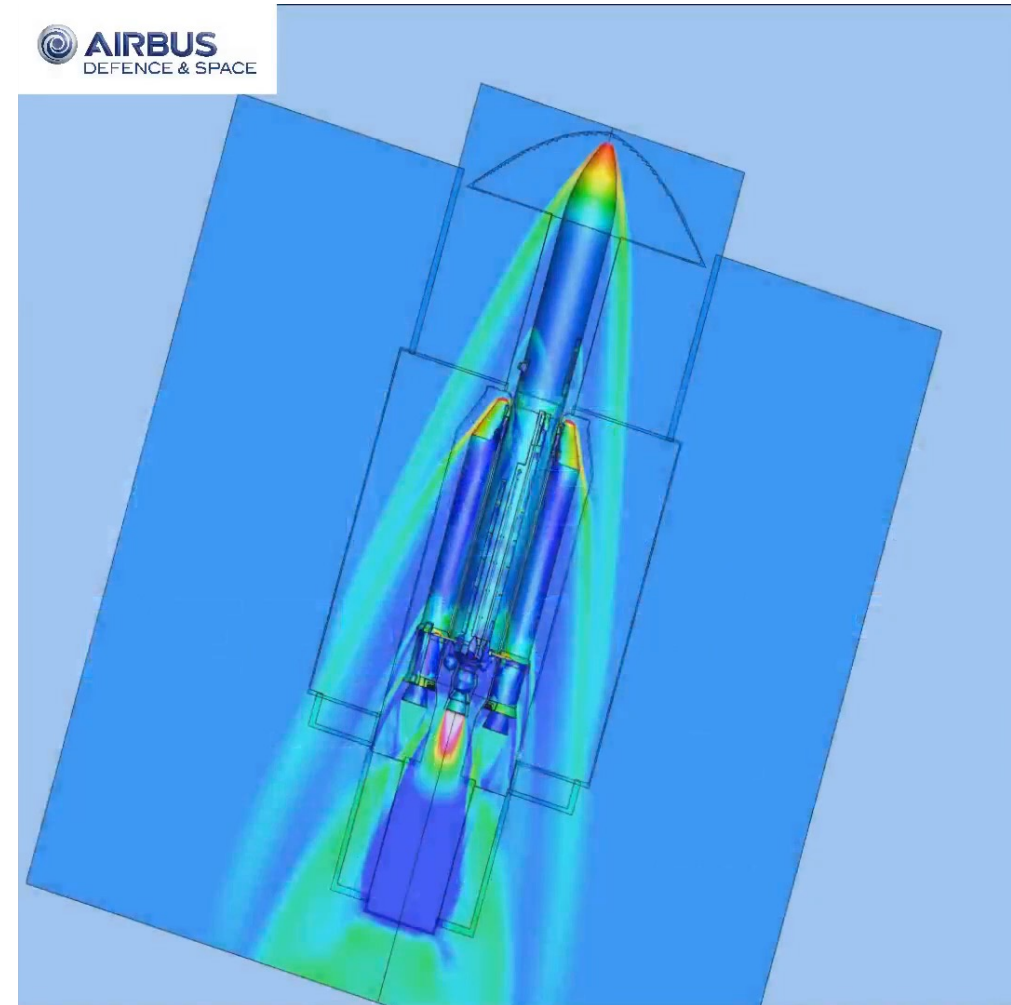
Data structures for 3d meshes

The EasyPAP Team

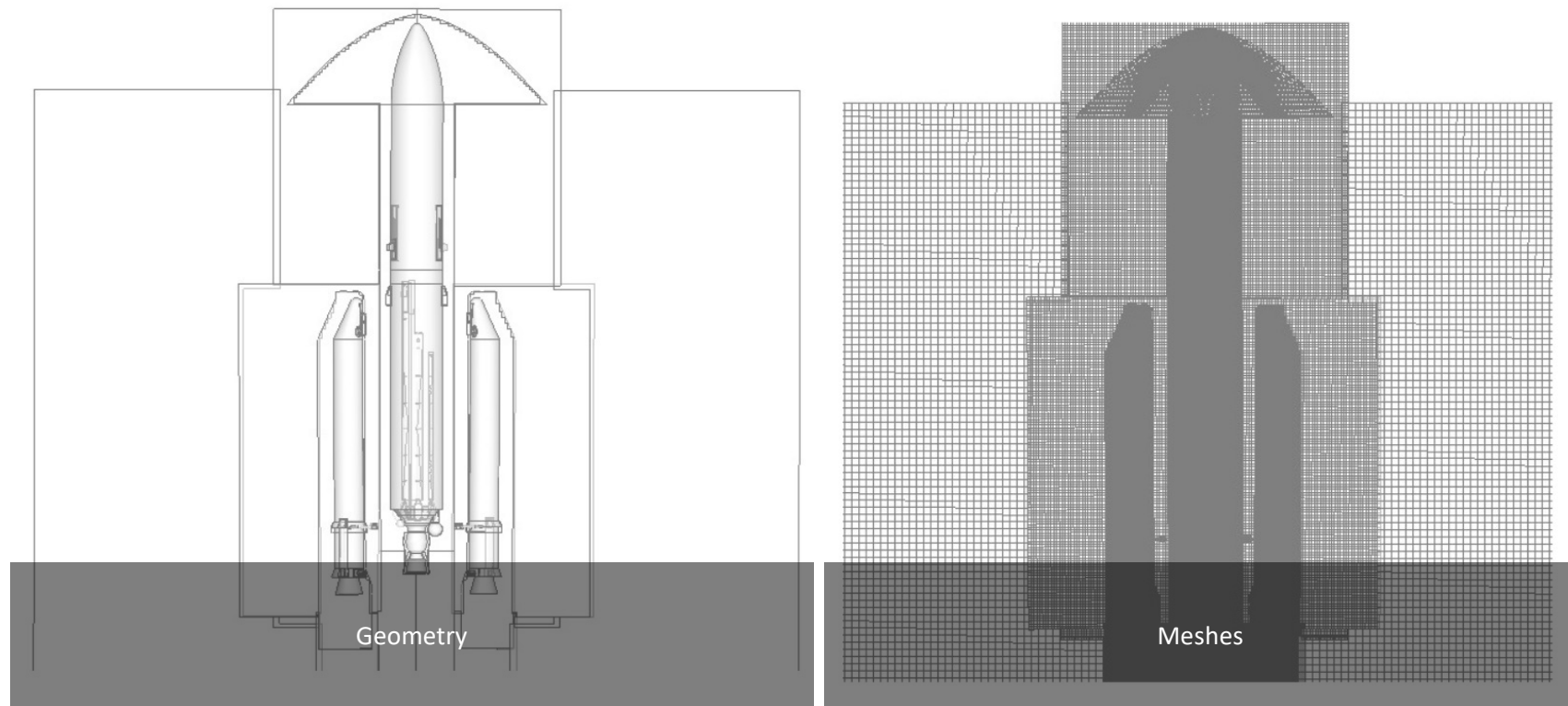


Numerical simulation

- Provide valuable insights and aiding in the understanding of complex fluid flow phenomena
 - difficult to analyze using analytical methods or physical experiments
 - blast wave propagation during rocket take-off
 - launch vehicle stage separations
 - noise generated by aircraft propellers



Numerical modeling of phenomena



About Meshes

- Meshes com from .OBJ files
 - Straightforward text format
 - Vertices, faces, connectivity
 - [+ default partitioning]

```
v 1.3764 0.76354 0.0236
```

```
...
```

```
f 0 1 2
```

```
f 0 2 3
```

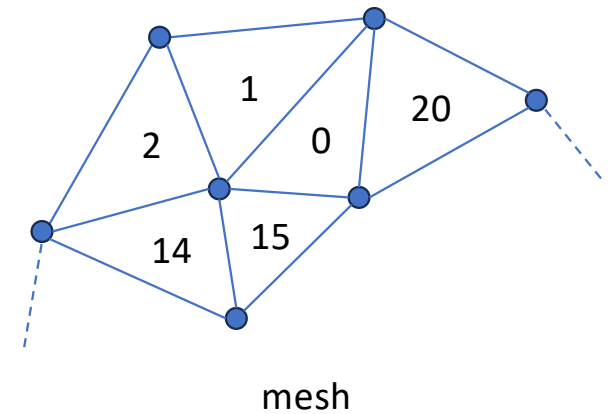
```
...
```

```
n 1 15 20
```

```
n 0 2
```

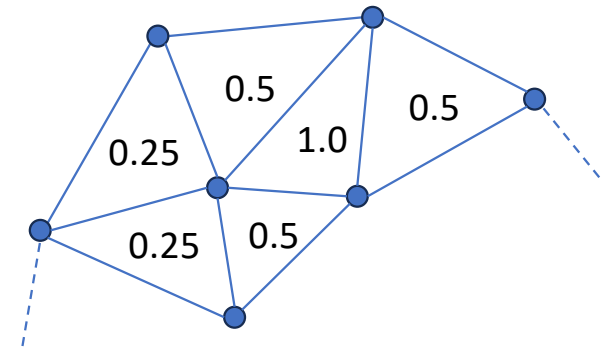
```
...
```

- Most information is only used for 3D display



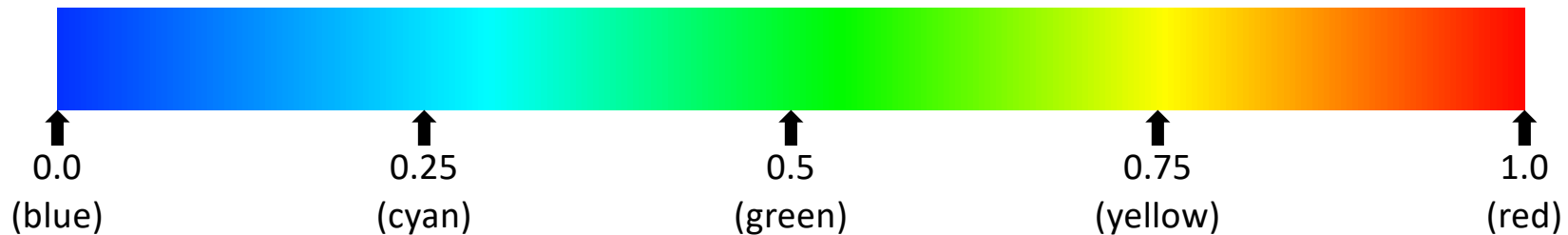
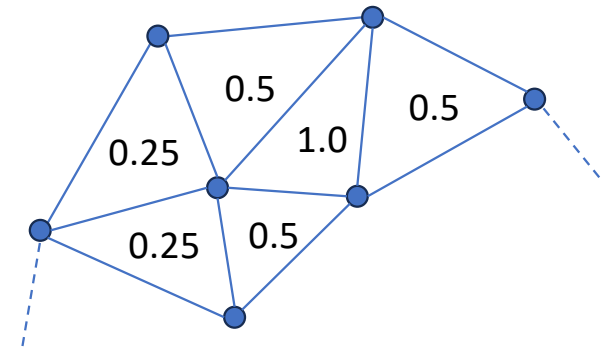
Doing computations on unstructured meshes

- A value representing a physical quantity (e.g. temperature) is attached to each cell
 - Normalized in $[0.0..1.0]$



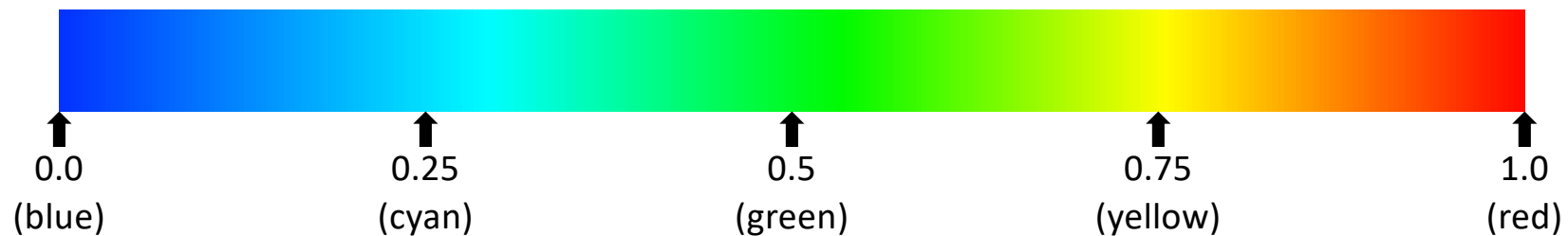
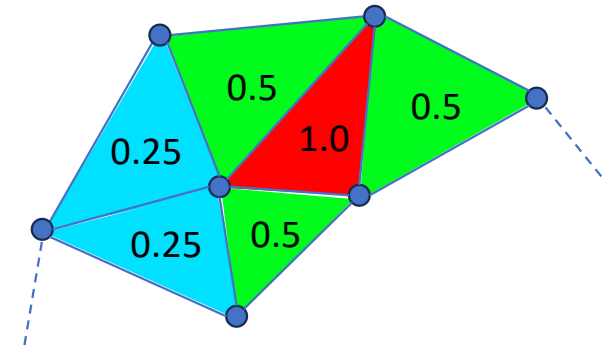
Doing computations on unstructured meshes

- A value representing a physical quantity (e.g. temperature) is attached to each cell
 - Normalized in $[0.0..1.0]$
- Cells are colored by interpolation using a gradient palette



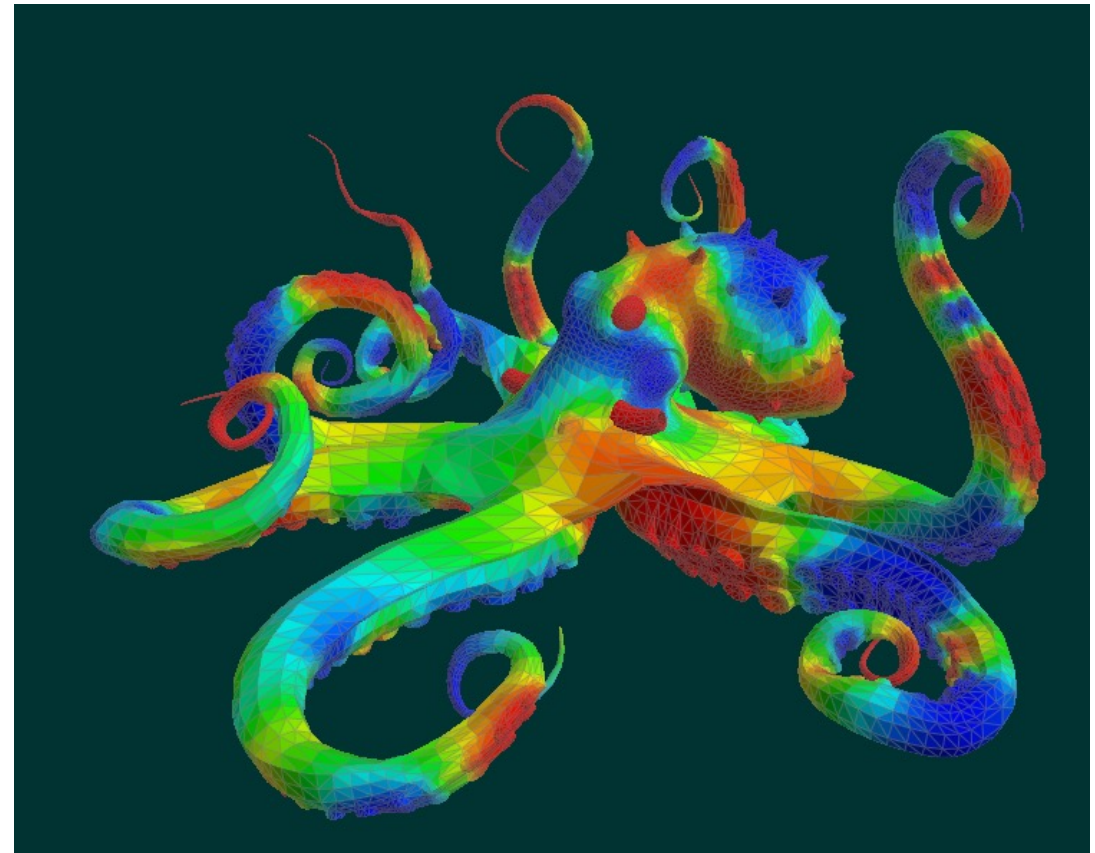
Doing computations on unstructured meshes

- A value representing a physical quantity (e.g. temperature) is attached to each cell
 - Normalized in $[0.0..1.0]$
- Cells are colored by interpolation using a gradient palette



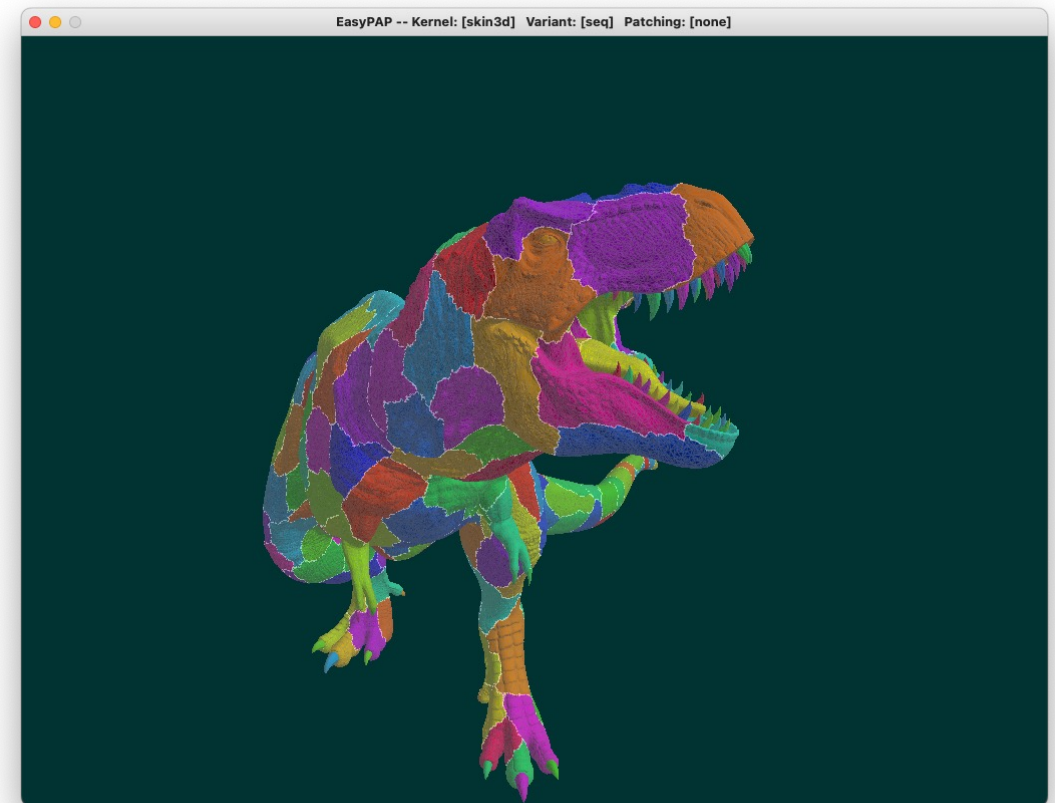
Doing computations on unstructured meshes

- A value representing a physical quantity (e.g. temperature) is attached to each cell
 - Normalized in $[0.0..1.0]$
- Cells are colored by interpolation using a gradient palette



Working with meshes in EasyPAP

- Pixels → Cells
 - Variable number of neighbors
- Colors → float values
- In EasyPAP, the programmer sees
 - `NB_CELLS`
 - `cur_data` (cell) and `next_data` (cell)
 - Arrays of floating-point values
 - Remember: values must be in range 0.0-1.0



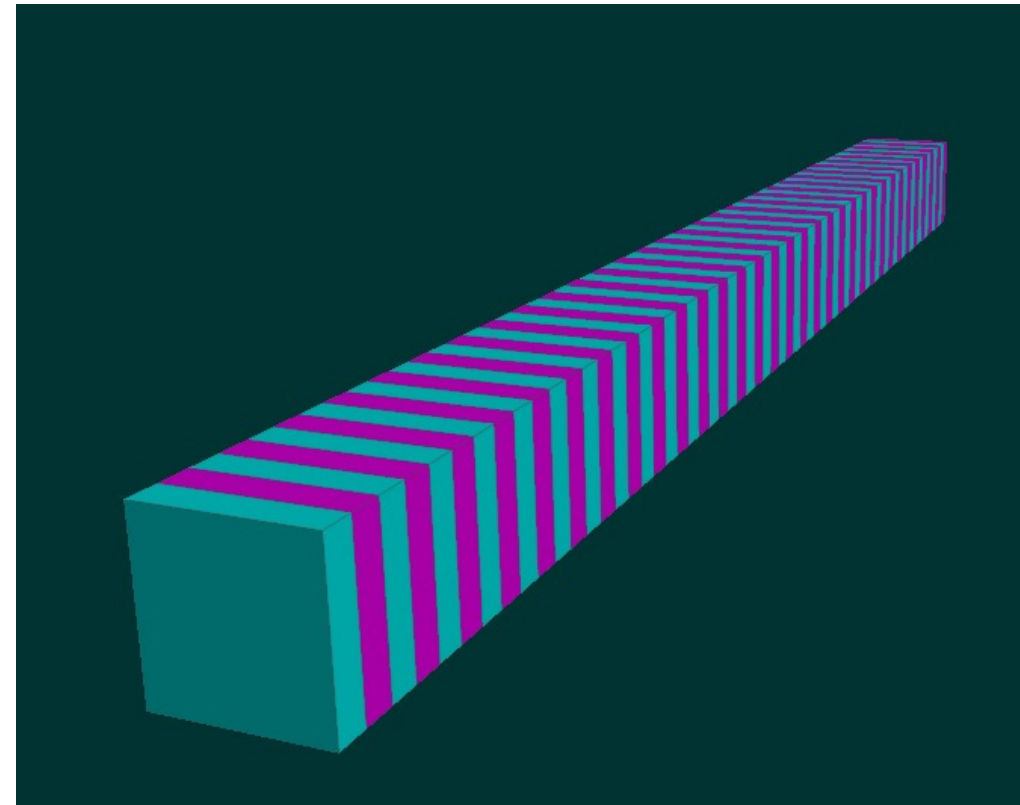
Setting a simple 2-point palette

```
void sample3d_config (char *param)
{
    // Choose color palette
    float colors[] = {0.0f, 0.8f, 0.8f, 1.f,  // cyan
                     0.8f, 0.0f, 0.8f, 1.f}; // pink
    mesh_data_set_palette (colors, 2);
}
```

Example alternating 0 and 1

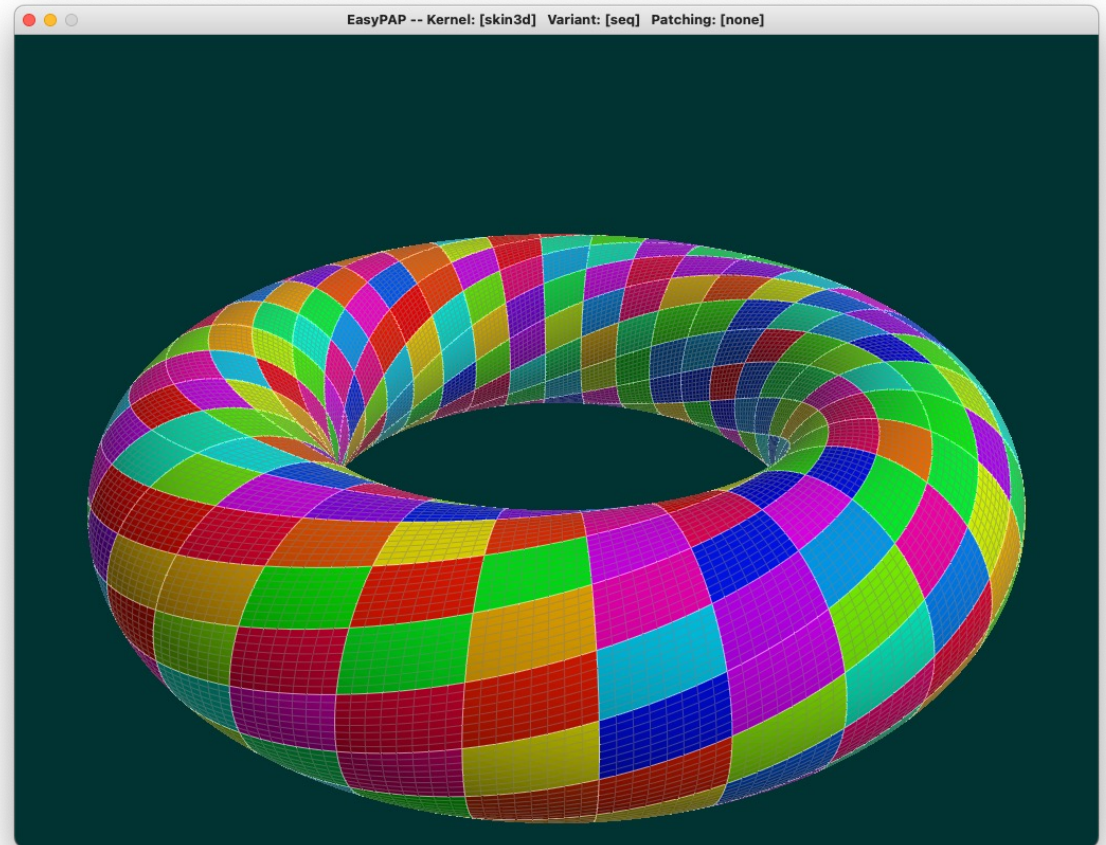
```
//////////////////// Sequential version (seq)
// Suggested cmdline:
// ./run -lm <mesh_file> -k sample3d -si
unsigned sample3d_compute_seq (unsigned nb_iter)
{
    for (unsigned it = 1; it <= nb_iter; it++)
        for (int c = 0; c < NB_CELLS; c++)
            cur_data (c) = (float)(c & 1);

    // Stop after first iteration
    return 1;
}
```



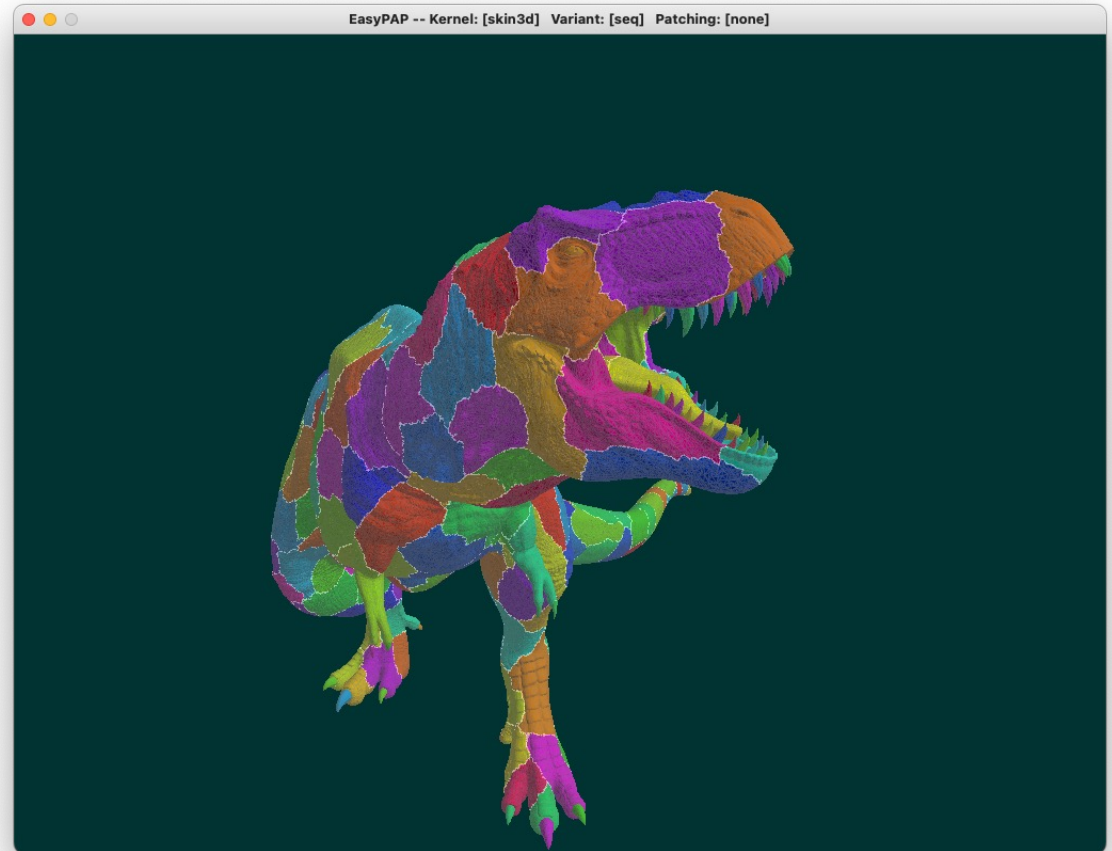
Where are my tiles?

- Pixels → Cells
 - Variable number of neighbors
- Colors → float values
- Tiles → Patches
 - Obtained either by
 - Space filling curves
 - Scotch partitioning library



Where are my tiles?

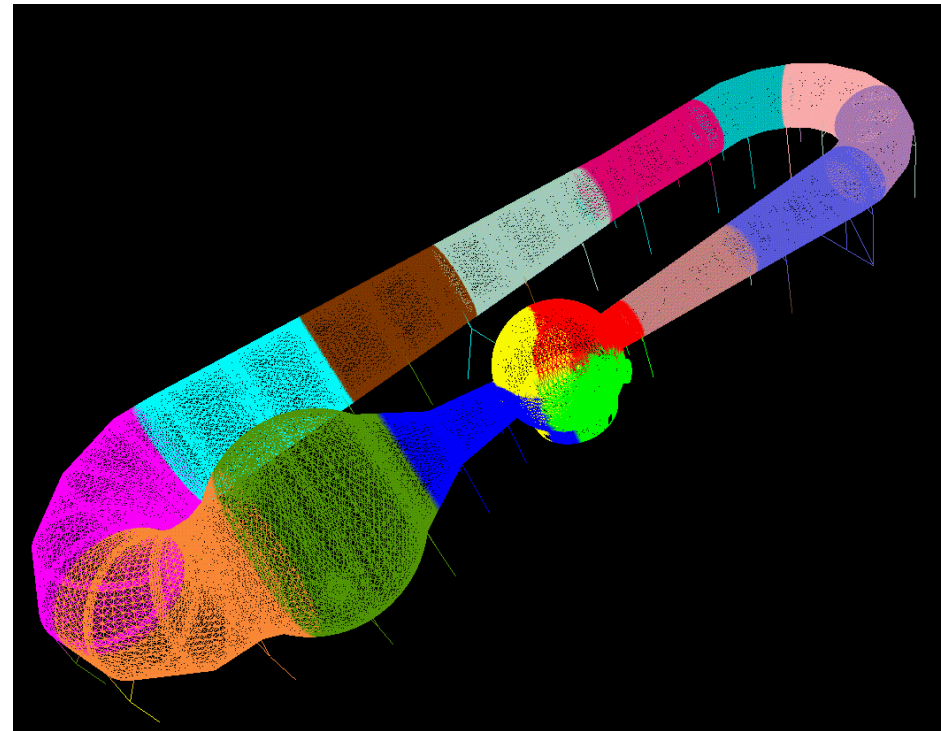
- Pixels → Cells
 - Variable number of neighbors
- Colors → float values
- Tiles → Patches
 - Obtained either by
 - Space filling curves
 - **Scotch partitioning library**



The Scotch Graph Partitioner

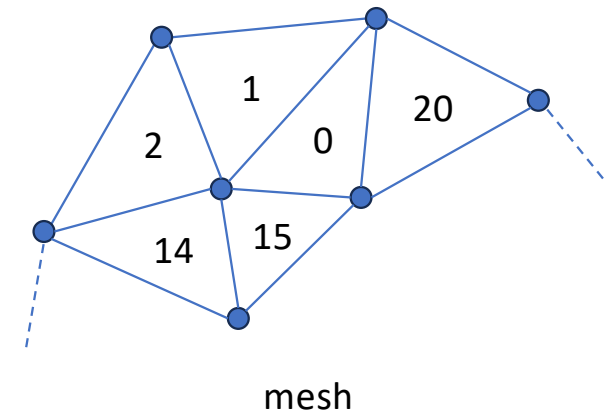


- Scotch is a graph partitioning library
 - F. Pellegrini, Univ. Bordeaux
- It optimizes workload distribution effectively
- Scotch is designed for parallel computing environments
 - It offers multiple efficient and flexible algorithms.
 - The library supports multiple graph formats.

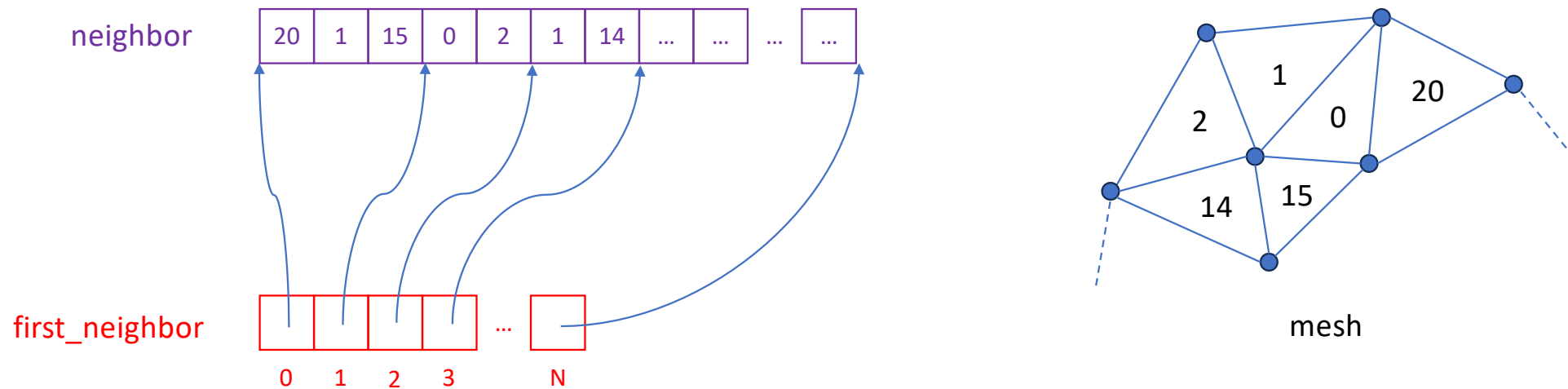


Accessing mesh connectivity

- In EasyPAP, the programmer sees
 - `NB_CELLS`
 - `cur_data (cell)` and `next_data (cell)`
- And
 - `nb_neighbors (int cell)`
 - `nth_neighbor (int cell, int n)`
 - `max_neighbors ()`
 - Max connectivity in the whole graph



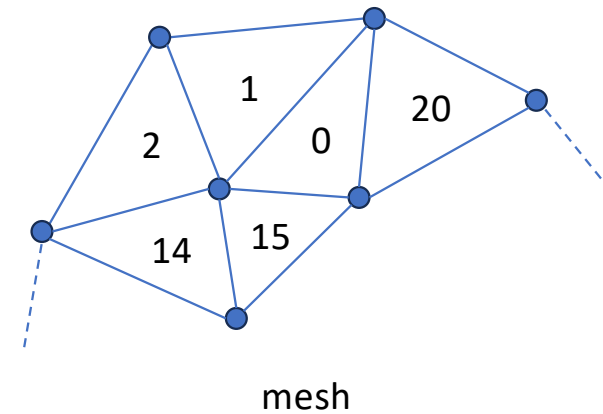
Mesh connectivity:
a “compact edge array” is used by default



Neighbors of cell #i are stored in `neighbors [first_neighbor[i] .. first_neighbor [i+1] - 1]`

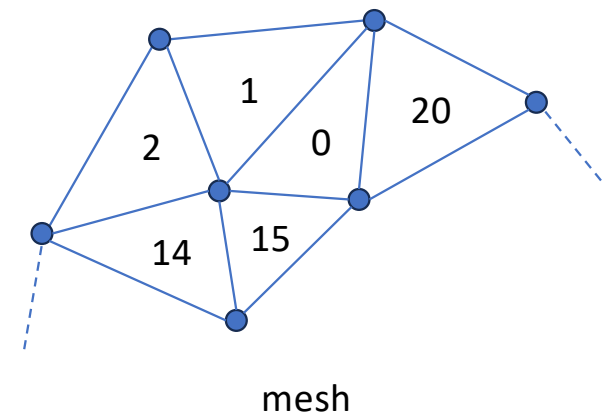
Mesh connectivity

- Programmers can directly access the compact edge array
 - `neighbor_start` (int cell)
 - Index of first neighbor
 - `neighbor_end` (int cell)
 - Index of last neighbor + 1
 - `neighbor` (int index)



Accessing mesh connectivity in EasyPAP

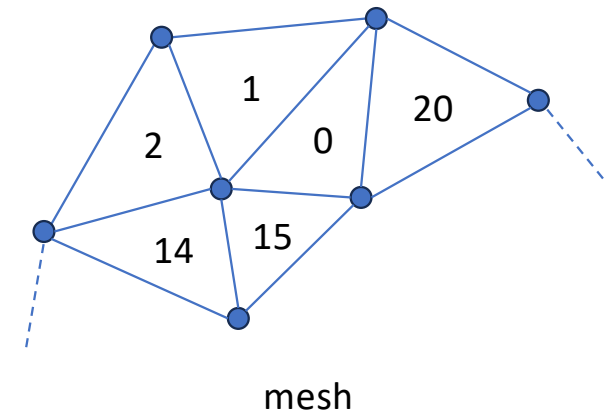
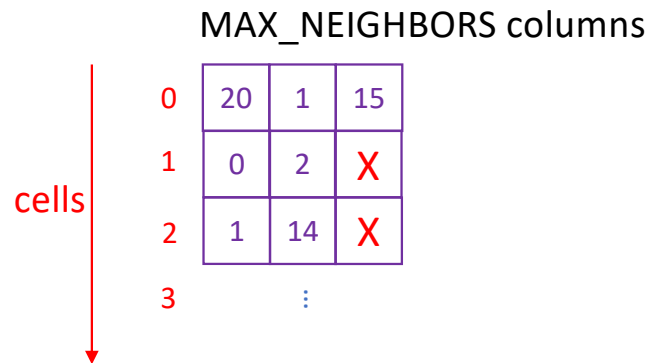
```
for (int nn = 0; nn < nb_neighbors (c); nn++) {  
    int n = nth_neighbor (c, nn);  
    float value = cur_data (n);  
    ...  
}  
// is equivalent to  
for (int id = neighbor_start (c);  
     id < neighbor_end (c);  
     id++) {  
    int n = neighbor (id);  
    float value = cur_data (n);  
    ...  
}
```



Towards a more regular data structure for GPUs and vector instructions

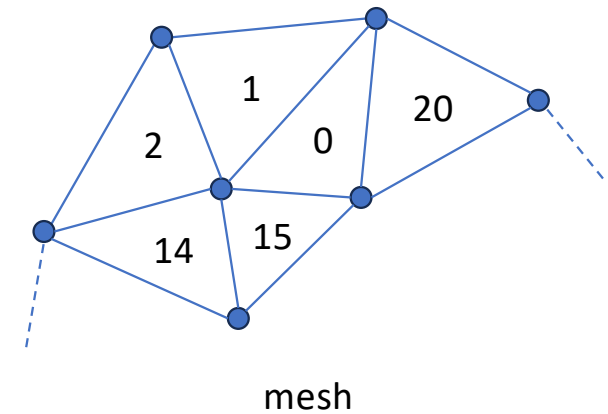
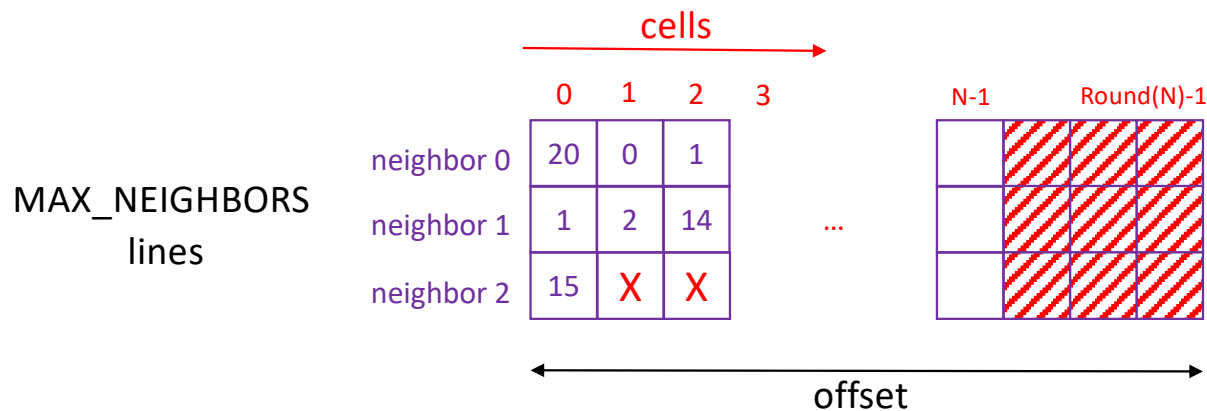
- Idea

- MAX_NEIGHBORS is known
- We can waste a little space and use a 2D array



A SoA layout would better meet our needs

- 'neighbors_soa' is a 1D array padded for alignment purposes



This is what is used by default in AVX and OpenCL implementations